

COMBINATORICS OF RATIONAL FUNCTIONS AND POINCARÉ-BIRKHOFF-WITT EXPANSIONS OF THE CANONICAL $U(\mathfrak{n}_-)$ -VALUED DIFFERENTIAL FORM

R. RIMÁNYI, L. STEVENS, AND A. VARCHENKO

ABSTRACT. We study the canonical $U(\mathfrak{n}_-)$ -valued differential form, whose projections to different Kac-Moody algebras are key ingredients of the hypergeometric integral solutions of KZ-type differential equations and Bethe ansatz constructions. We explicitly determine the coefficients of the projections in the simple Lie algebras A_r, B_r, C_r, D_r in a conveniently chosen Poincaré-Birkhoff-Witt basis.

1. INTRODUCTION

For a Kac-Moody algebra \mathfrak{g} , let V be the tensor product $V_{\Lambda_1} \otimes \dots \otimes V_{\Lambda_n}$ of highest weight \mathfrak{g} -modules. The V -valued hypergeometric solutions of Knizhnik-Zamolodchikov-type differential equations have the form [SV1], [SV2]:

$$(1) \quad I(z) = \int_{\gamma(z)} \Phi(t, z) \Omega^V(t, z) .$$

Here $t = (t_1, \dots, t_k)$, $z = (z_1, \dots, z_n)$, Φ is a scalar multi-valued (master) function, $\gamma(z)$ is a suitable cycle in t -space depending on z , and Ω^V is a V -valued rational differential k -form.

The same Φ and Ω^V have applications to the Bethe Ansatz method. It is known [RV] that the values of Ω^V at the critical points of Φ (with respect to t) give eigenvectors of the Hamiltonians of the Gaudin model associated with V .

For every $V = V_{\Lambda_1} \otimes \dots \otimes V_{\Lambda_n}$, the V -valued differential form Ω^V is constructed out of a single $U(\mathfrak{n}_-)$ -valued differential form $\Omega^{\mathfrak{g}}$, where $\mathfrak{g} = \mathfrak{n}_- \oplus \mathfrak{h} \oplus \mathfrak{n}_+$ is the Cartan decomposition of \mathfrak{g} , and $U(\mathfrak{n}_-)$ denotes the universal enveloping algebra of the Lie algebra \mathfrak{n}_- , see Appendix. In applications, it is important to have convenient formulas for $\Omega^{\mathfrak{g}}$, and this is the goal of the present paper.

In [Mat], Matsuo suggested a formula $\int \Phi(t, z) \tilde{\Omega}^V(t, z)$ for solutions of the KZ equations for $\mathfrak{g} = \mathfrak{sl}_{r+1}$. His differential form $\tilde{\Omega}^V$ also can be constructed from a $U(\mathfrak{n}_-)$ -valued form $\tilde{\Omega}^{\mathfrak{sl}_{r+1}}$ in

Supported by NSF grant DMS-0405723 (1st author), DMS-0244579 (3rd author)
 Keywords: canonical differential form, KZ equation, Bethe ansatz, PBW-expansion, symmetric rational functions
 AMS Subject classification 33C67.

the same way as Ω^V from $\Omega^{\mathfrak{g}}$. It is known that for sl_2 , the two forms

$$\begin{aligned}\Omega^{sl_2} &= \sum_{k=0}^{\infty} \left(\sum_{\pi \in \Sigma_k} \text{sgn}(\pi) \cdot \frac{dt_{\pi(1)}}{t_{\pi(1)}} \wedge \frac{d(t_{\pi(2)} - t_{\pi(1)})}{t_{\pi(2)} - t_{\pi(1)}} \wedge \dots \wedge \frac{d(t_{\pi(k)} - t_{\pi(k-1)})}{t_{\pi(k)} - t_{\pi(k-1)}} \right) \otimes f^k, \\ \tilde{\Omega}^{sl_2} &= \sum_{k=0}^{\infty} \left(\bigwedge_{i=1}^k \frac{dt_i}{t_i} \right) \otimes f^k\end{aligned}$$

coincide. For $r > 1$, the form $\Omega^{sl_{r+1}}$ is a polynomial in f_1, \dots, f_r with scalar differential forms as coefficients, while the Matsuo form $\tilde{\Omega}^{sl_{r+1}}$ is a sum over a Poincaré-Birkhoff-Witt basis of $U(\mathfrak{n}_-)$ with coefficients of the same type. Both forms have some advantages. The form $\Omega^{\mathfrak{g}}$ is given by the same formula for any \mathfrak{g} . The formula for $\tilde{\Omega}^{sl_{r+1}}$ has less terms and less apparent poles (see above for the apparent poles at $t_i - t_j = 0$). The advantage of having an expression in terms of a PBW basis is most spectacular for representations with 1-dimensional weight-subspaces.

In this paper, we prove that $\tilde{\Omega}^{sl_{r+1}} = \Omega^{sl_{r+1}}$ and give similar Poincaré-Birkhoff-Witt expansions for the differential form $\Omega^{\mathfrak{g}}$ for the simple Lie algebras \mathfrak{g} of types B_r, C_r, D_r .

As a byproduct, we obtain results on the combinatorics of rational functions. Namely, some non-trivial identities are established among certain rational functions with partial symmetries. The results are far reaching generalizations of the prototype of these formulas, the ‘‘Jacobi-identity’’

$$\frac{1}{(x-y)(x-z)} + \frac{1}{(y-x)(y-z)} + \frac{1}{(z-x)(z-y)} = 0.$$

In all A_r, B_r, C_r, D_r cases, the coefficients of $\Omega^{\mathfrak{g}}$ can be encoded by diagrams relevant to sub-diagrams of the Dynkin diagram of \mathfrak{g} . One may expect that the same phenomenon occurs in a more general Kac-Moody setting, too.

According to the formulas for Φ and Ω^V in [SV1], [SV2], the poles of Ω^V contain the singularities of Φ . From our PBW expansion formulas, it follows that the poles of Ω^V *coincide* with the singularities of Φ , hence it makes sense to consider the values of Ω^V at (e.g.) the critical points of Φ , as is needed in the Bethe ansatz applications.

It was shown in [MaV] that the Matsuo type hypergeometric solutions of the sl_{r+1} KZ-equations satisfy the complementary dynamical difference equations. According to our result $\Omega^{sl_{r+1}} = \tilde{\Omega}^{sl_{r+1}}$, the hypergeometric solutions (1) also satisfy the dynamical difference equation for $\mathfrak{g} = sl_{r+1}$.

In [FV], the hypergeometric solutions $I(z, \lambda) = \int \Phi^{ell}(t, z) \Omega^{V, ell}(t, z, \lambda)$ of the KZB equations were constructed. Here Φ^{ell} is the elliptic scalar master function depending on the same variables t, z as Φ , and $\Omega^{V, ell}(t, z, \lambda)$ is the elliptic analogue of Ω^V , which is a V -valued differential form depending also on $\lambda \in \mathfrak{h}$. It would be useful to find PBW type expansions of $\Omega^{V, ell}$ similar to our PBW expansions of Ω^V .

The hypergeometric solutions of qKZ, the quantum version of KZ equations, for sl_{r+1} -modules V were described in [TV1], [TV2] as $I(z) = \int \Phi_q(t, z) \Omega_q^V(t, z)$. There the V -valued differential form Ω_q^V was given in a PBW expansion. Our PBW formulas for the B, C, D series may suggest integral formulas for solutions of B, C, D type qKZ equations.

The structure of the cycles γ in (1) for arbitrary \mathfrak{g} was analyzed in [V1]. The cycles were presented as linear combinations of multiple loops, and that presentation established a connection between multi-loops and monomials $f_{i_k} \dots f_{i_1}$ in $U_q(\mathfrak{n}_-)$, where $U_q(\mathfrak{n}_-)$ is the \mathfrak{n}_- -part of the quantum group $U_q(\mathfrak{g})$. That connection in particular gives an identification of the monodromy of the KZ equations with the R -matrix representations associated with $U_q(\mathfrak{g})$. Our PBW expansions of $\Omega^{\mathfrak{g}}$ suggest that there might be an interesting PBW type geometric theory of cycles for each \mathfrak{g} , in which the cycles are presented by linear combinations of cells corresponding to elements of the PBW basis in the corresponding $U_q(\mathfrak{n}_-)$.

It would also be interesting to compare our PBW formulas with Cherednik's formulas for solutions of the trigonometric KZ equations [Ch].

The authors thank D. Cohen for helpful discussions.

2. SYMMETRIZERS, SIGNS AND OTHER CONVENTIONS

2.1. Symmetrizers. For a nonnegative integer r and $k = (k_1, \dots, k_r) \in \mathbb{N}^r = \{0, 1, 2, \dots\}^r$, we will often consider various 'objects' $x(t_j^{(i)})$ (functions, differential forms, flags), depending on the r sets of variables

$$(2) \quad t_1^{(1)}, t_2^{(1)}, \dots, t_{k_1}^{(1)}, \quad t_1^{(2)}, t_2^{(2)}, \dots, t_{k_2}^{(2)}, \quad \dots \quad t_1^{(r)}, t_2^{(r)}, \dots, t_{k_r}^{(r)}.$$

Let G_k be the product $\prod_i \Sigma_{k_i}$ of symmetric groups. We define the action of $\pi \in G_k$ on x by permuting the $t_j^{(i)}$'s with the same upper indices. Then we define the symmetrizer and antisymmetrizer operators

$$\text{Sym}_k x(t_j^{(i)}) = \sum_{\pi \in G_k} \pi \cdot x, \quad \text{ASym}_k x(t_j^{(i)}) = \sum_{\pi \in G_k} \text{sgn}(\pi) \pi \cdot x.$$

Let $|k| = \sum_i k_i$. For a function ('multi-index') $J : \{1, \dots, |k|\} \rightarrow \{1, \dots, r\}$ with $\#J^{-1}(i) = k_i$, let $c : \{1, \dots, |k|\} \rightarrow \mathbb{N}$ be the unique map whose restriction to $J^{-1}(i)$ is the increasing function onto $\{1, \dots, k_i\}$. Then J defines an identification of $(t_1, \dots, t_{|k|})$ with the variables in (2) by identifying

$$(3) \quad t_u \quad \text{with} \quad t_{c(u)}^{(J(u))}.$$

Thus, if x depends on $t_1, \dots, t_{|k|}$ and J is given, we can consider x depending on the variables in (2). For example, we can (anti)symmetrize x :

$$\text{Sym}_k^J x(t_u) = \text{Sym}_k x(t_j^{(i)}), \quad \text{ASym}_k^J x(t_u) = \text{ASym}_k x(t_j^{(i)}).$$

2.2. The sign of a multi-index; volume forms. Let J_0 be the unique *increasing* function $\{1, \dots, |k|\} \rightarrow \{1, \dots, r\}$ with $\#J_0^{-1}(i) = k_i$, and let J be any function $\{1, \dots, |k|\} \rightarrow \{1, \dots, r\}$ with $\#J^{-1}(i) = k_i$. Then the identifications defined in (3) for J and J_0 together define a permutation of $1, \dots, |k|$. The sign of this permutation will be denoted by $\text{sgn}(J)$. E.g. $\text{sgn}(1 \mapsto 1, 2 \mapsto 1, 3 \mapsto 2) = 1$, $\text{sgn}(1 \mapsto 1, 2 \mapsto 2, 3 \mapsto 1) = -1$.

Define the 'standard volume form' dV_k to be $dt_1^{(1)} \wedge \dots \wedge dt_{k_1}^{(1)} \wedge dt_1^{(2)} \wedge \dots \wedge dt_{k_2}^{(2)} \wedge \dots \wedge dt_1^{(r)} \wedge \dots \wedge dt_{k_r}^{(r)}$. Observe that if we use the identification (3), then $dt_1 \wedge dt_2 \wedge \dots \wedge dt_{|k|}$ is equal to $\text{sgn}(J) \cdot dV_k$.

2.3. The star multiplication. For $k \in \mathbb{N}^r$, let \mathcal{F}_k be the vector space of rational functions in the variables in (2) which are symmetric under the action of G_k . We define a multiplication (c.f. [V2, 6.4.2]) $*$: $\mathcal{F}_k \otimes \mathcal{F}_l \rightarrow \mathcal{F}_{k+l}$ by

$$(f * g)(t_1^{(1)}, \dots, t_{k_1+l_1}^{(1)}, \dots, t_1^{(r)}, \dots, t_{k_r+l_r}^{(r)}) = \frac{1}{\prod_i k_i! l_i!} \text{Sym}_{k+l} \left(f(t_1^{(1)}, \dots, t_{k_1}^{(1)}, \dots, t_1^{(r)}, \dots, t_{k_r}^{(r)}) \cdot g(t_{k_1+1}^{(1)}, \dots, t_{k_1+l_1}^{(1)}, \dots, t_{k_r+1}^{(r)}, \dots, t_{k_r+l_r}^{(r)}) \right).$$

For example, if we write t for $t^{(1)}$ and s for $t^{(2)}$, then

$$\frac{1}{t_1 t_2} * \frac{1}{t_1(s-t_1)} = \frac{1}{t_1 t_2} \cdot \frac{1}{t_3(s-t_3)} + \frac{1}{t_1 t_3} \cdot \frac{1}{t_2(s-t_2)} + \frac{1}{t_2 t_3} \cdot \frac{1}{t_1(s-t_1)}.$$

This multiplication makes $\bigoplus_k \mathcal{F}_k$ an associative and commutative algebra.

3. ARRANGEMENTS. THE ORLIK-SOLOMON ALGEBRA AND ITS DUAL. DISCRIMINANTAL ARRANGEMENTS AND THEIR SYMMETRIES

Let \mathcal{C} be a hyperplane arrangement in \mathbb{C}^n . In this section we recall two algebraic descriptions of the cohomology of the complement $U = \mathbb{C}^n - \bigcup_{H \in \mathcal{C}} H$, as well as properties of the discriminantal arrangement which will be needed later. The general reference is [SV2].

3.1. The Orlik-Solomon algebra. For $H \in \mathcal{C}$, let ω_H be the logarithmic differential form df_H/f_H , where $f_H = 0$ is a defining equation of H . Let $\mathcal{A} = \mathcal{A}(\mathcal{C})$ be the graded \mathbb{C} -algebra with unit element generated by all ω_H 's, $H \in \mathcal{C}$. The elements of \mathcal{A} are closed forms on U , hence they determine cohomology classes. According to Arnold and Brieskorn, the induced map $\mathcal{A} \rightarrow H^*(U; \mathbb{C})$ is an isomorphism. The degree p part of \mathcal{A} will be denoted by \mathcal{A}^p .

3.2. Flags. Non-empty intersections of hyperplanes in \mathcal{C} are called edges. A p -flag of \mathcal{C} is a chain of edges

$$F = [\mathbb{C}^n = L^0 \supset L^1 \supset L^2 \supset \dots \supset L^{p-1} \supset L^p],$$

where $\text{codim } L^i = i$. Consider the complex vector space generated by all p -flags of \mathcal{C} modulo the relations

$$\sum_L [L^0 \supset \dots \supset L^{i-1} \supset L \supset L^{i+1} \supset \dots \supset L^p] = 0, \quad (0 < i < p),$$

where the summation runs over all $\text{codim } i$ edges L that contain L^{i+1} and are contained in L^{i-1} . This vector space is denoted by $Fl^p = Fl^p(\mathcal{C})$, and let Fl be the direct sum $\bigoplus_p Fl^p$.

3.3. Iterated residues. According to [SV2, Th. 2.4], \mathcal{A} and Fl are dual graded vector spaces. The value of a differential form on a flag is given by an iterated residue operation

$$\text{Res} : Fl \otimes \mathcal{A} \rightarrow \mathbb{C},$$

defined as follows. Let $F = [L^i]$ be a p -flag and $\omega \in \mathcal{A}$ a p -form on U . Then

$$\text{Res}_F \omega = \text{Res}_{L^p} \left(\text{Res}_{L^{p-1}} \left(\dots \text{Res}_{L^2} (\text{Res}_{L^1}(\omega)) \dots \right) \right) \in \mathbb{C}.$$

3.4. The discriminantal arrangement and its symmetries. The discriminantal arrangement \mathcal{C}^n in \mathbb{C}^n is defined as the collection of hyperplanes

$$t_i = 0 \quad (i = 1, \dots, n) \quad \text{and} \quad t_i - t_j = 0 \quad (1 \leq i < j \leq n).$$

Let us fix r non-negative integers (weights) $k = (k_1, \dots, k_r)$ with $\sum k_i = |k|$ and consider $\mathbb{C}^{|k|}$ with coordinates

$$(t_1^{(1)}, \dots, t_{k_1}^{(1)}, t_1^{(2)}, \dots, t_{k_2}^{(2)}, \dots, t_1^{(r)}, \dots, t_{k_r}^{(r)}).$$

The group $G_k = \prod \Sigma_{k_i}$ then acts on $\mathbb{C}^{|k|}$ (by permuting the coordinates with the same upper indices) which then induces an action of G_k on $\mathcal{A}(\mathcal{C}^{|k|})$ and $Fl(\mathcal{C}^{|k|})$.

The skew-invariant subspaces (i.e. the collection of x 's for which $\pi \cdot x = \text{sgn}(\pi)x \forall \pi \in G_k$) of $\mathcal{A}^{|k|}(\mathcal{C}^{|k|})$ and $Fl^{|k|}(\mathcal{C}^{|k|})$ will be denoted by \mathcal{A}^{G_k} and Fl^{G_k} , respectively. The duality stated in 3.3 is consistent with the group-action in the sense that \mathcal{A}^{G_k} and Fl^{G_k} are dual vector spaces.

3.5. Flags of the discriminantal arrangement. Let U_r be the free associative algebra generated by r symbols $\tilde{f}_1, \tilde{f}_2, \dots, \tilde{f}_r$. It is multigraded by \mathbb{N}^r ; the (k_1, \dots, k_r) -degree part will be denoted by $U_r[k] = U_r[k_1, \dots, k_r]$. For any non-zero homogeneous element in $U_r[k]$, we define its *content* to be k . It is proved in [SV2, Th. 5.9] that $U_r[k]$ is isomorphic to Fl^{G_k} under the following map. For $J : \{1, \dots, |k|\} \rightarrow \{1, \dots, r\}$ with $\#J^{-1}(i) = k_i$, the monomial $\tilde{f}_J = \tilde{f}_{J(|k|)} \tilde{f}_{J(|k|-1)} \dots \tilde{f}_{J(2)} \tilde{f}_{J(1)} \in U_r[k_1, \dots, k_r]$ corresponds to $\frac{\text{sgn}(J)}{\prod_i k_i!} \text{ASym}_k^J(F) \in Fl^{G_k}$, where F is the $|k|$ -flag

$$[\mathbb{C}^{|k|} \supset (t_1 = 0) \supset (t_1 = t_2 = 0) \supset \dots \supset (t_1 = \dots = t_{|k|-1} = 0) \supset (t_1 = \dots = t_{|k|} = 0)]$$

with its variables t_u identified with $t_j^{(i)}$'s as defined by (3).

Example 3.1. For $r = 2$, $k = (1, 1)$, we have the correspondence

$$\tilde{f}_2 \tilde{f}_1 \leftrightarrow [\mathbb{C}^2 \supset (t_1^{(1)} = 0) \supset (t_1^{(1)} = t_1^{(2)} = 0)], \quad \tilde{f}_1 \tilde{f}_2 \leftrightarrow -[\mathbb{C}^2 \supset (t_1^{(2)} = 0) \supset (t_1^{(2)} = t_1^{(1)} = 0)].$$

For $r = 2$, $k = (2, 1)$, we have the correspondence

$$\tilde{f}_1^2 \tilde{f}_2 \leftrightarrow \frac{1}{2} \left([\mathbb{C}^3 \supset (t_1^{(2)} = 0) \supset (t_1^{(2)} = t_1^{(1)} = 0) \supset (t_1^{(2)} = t_1^{(1)} = t_2^{(1)} = 0)] - [\mathbb{C}^3 \supset (t_1^{(2)} = 0) \supset (t_1^{(2)} = t_2^{(1)} = 0) \supset (t_1^{(2)} = t_2^{(1)} = t_1^{(1)} = 0)] \right).$$

4. THE CANONICAL DIFFERENTIAL FORM

Using the identifications of Section 3, the tensor product

$$\mathcal{A}^{G_k} \otimes U_r[k_1, \dots, k_r]$$

is the tensor product of a vector space with its dual space. Therefore the canonical element, $\sum_i b_i^* \otimes b_i$ for any basis $\{b_i\}$ of $U_r[k]$ and the dual basis $\{b_i^*\}$ of \mathcal{A}^{G_k} , is well defined—it does not depend on the choice of the basis of $U_r[k]$. We will call this element the *canonical differential form of weight k* and denote it by Ω_k . Tracing back the identifications of Section 3, we get the explicit form.

Theorem 4.1. [SV2] *Let $t_0 = 0$. The canonical differential form is*

$$\begin{aligned}\Omega_k &= \sum_J \operatorname{sgn}(J) \cdot \operatorname{ASym}_k^J \left(\bigwedge_{u=1}^{|k|} d\log(t_u - t_{u-1}) \right) \otimes \tilde{f}_J \\ &= \sum_J \operatorname{Sym}_k^J \left(\prod_{u=1}^{|k|} \frac{1}{t_u - t_{u-1}} \right) dV_k \otimes \tilde{f}_J \quad \in \mathcal{A}^{G_k} \otimes U_r[k],\end{aligned}$$

where the summation runs over all $J : \{1, \dots, |k|\} \rightarrow \{1, \dots, r\}$ with $\#J^{-1}(i) = k_i$. (Recall that the variables t_u are identified with $t_i^{(j)}$'s using (3).)

Example 4.2. *Let $r = 2$, $k = (2, 1)$, and write t for $t^{(1)}$ and s for $t^{(2)}$. Then*

$$(4) \quad \begin{aligned}\Omega_{(2,1)} &= \left(\frac{1}{t_1(t_2 - t_1)(s - t_2)} + \frac{1}{t_2(t_1 - t_2)(s - t_1)} \right) dt_1 \wedge dt_2 \wedge ds \otimes \tilde{f}_2 \tilde{f}_1^2 + \\ &\quad \left(\frac{1}{t_1(s - t_1)(t_2 - s)} + \frac{1}{t_2(s - t_2)(t_1 - s)} \right) dt_1 \wedge dt_2 \wedge ds \otimes \tilde{f}_1 \tilde{f}_2 \tilde{f}_1 + \\ &\quad \left(\frac{1}{s(t_1 - s)(t_2 - t_1)} + \frac{1}{s(t_2 - s)(t_1 - t_2)} \right) dt_1 \wedge dt_2 \wedge ds \otimes \tilde{f}_1^2 \tilde{f}_2.\end{aligned}$$

Similar rational functions will often appear in this paper. It will be convenient to encode them with diagrams as follows: $\Omega_{(2,1)} =$

$$\operatorname{Sym} \left(* \begin{array}{c} t_1 \quad t_2 \quad s \\ \bullet \quad \bullet \quad \bullet \\ \hline \end{array} \right) dV_k \otimes \tilde{f}_2 \tilde{f}_1^2 + \operatorname{Sym} \left(* \begin{array}{c} t_1 \quad s \quad t_2 \\ \bullet \quad \bullet \quad \bullet \\ \hline \end{array} \right) dV_k \otimes \tilde{f}_1 \tilde{f}_2 \tilde{f}_1 + \operatorname{Sym} \left(* \begin{array}{c} s \quad t_1 \quad t_2 \\ \bullet \quad \bullet \quad \bullet \\ \hline \end{array} \right) dV_k \otimes \tilde{f}_1^2 \tilde{f}_2.$$

A rooted tree (root denoted by $*$) with variables associated to its vertices encodes the product of $1/(a - b)$'s for every edge whose vertices are decorated by a and b , and b is closer to the root of the tree. The label of the root of the tree is 0, so we do not write it out. The symmetrizer Sym is meant with respect to the content of the rational function.

5. PROPERTIES OF THE DIFFERENTIAL FORMS

In this section we present the two key properties needed in Section 6.

5.1. The residue of the canonical differential form. For $k = (k_1, \dots, k_r)$, we denote $(k_1, \dots, k_{i-1}, k_i - 1, k_{i+1}, \dots, k_r)$ by $k - 1_i$.

Lemma 5.1. *Let $k \in \mathbb{N}^r$ and $i \in [1, \dots, r]$. Then the maps*

$$R : \mathcal{A}^{G_k} \rightarrow \mathcal{A}^{G_{k-1_i}}, \quad \omega \mapsto \operatorname{Res}_{t_{k_i}^{(i)}=0} \omega,$$

and

$$\psi : U_r[k - 1_i] \rightarrow U_r[k], \quad x \mapsto (-1)^{k_1 + \dots + k_i - 1} x \tilde{f}_i,$$

are dual.

Proof. Let $\omega \in \mathcal{A}^{G_k}$ and $\tilde{f}_J \in U_r[k - 1_i]$. We need to check that the residue with respect to the flag corresponding to \tilde{f}_J of $\operatorname{Res}_{t_{k_i}^{(i)}=0} \omega$ is equal to $(-1)^{k_1 + \dots + k_i - 1}$ times the residue with respect to the flag corresponding to $\tilde{f}_J \tilde{f}_i$ of ω . This follows from the definitions (and the sign conventions). \square

Theorem 5.2.

$$\text{Res}_{t_{k_i}^{(i)}=0} \Omega_k = (-1)^{k_1+k_2+\dots+k_i-1} \cdot \Omega_{k-1_i} \cdot (1 \otimes \tilde{f}_i).$$

Proof. Let $\{b_u\}$ be a basis of $U_r[k-1_i]$, hence $\Omega_{k-1_i} = \sum b_u^* \otimes b_u$. Since the map ψ in Lemma 5.1 is an embedding, the images $\psi(b_u)$ can be extended to a basis $\{\psi(b_u), c_v\}$ of $U_r[k]$. Then $\Omega_k = \sum \psi(b_u)^* \otimes \psi(b_u) + \sum c_v^* \otimes c_v$. We have $(R \otimes 1)\Omega_k = \sum R(\psi(b_u)^*) \otimes \psi(b_u) + \sum R(c_v^*) \otimes c_v$, which, according to Lemma 5.1, is $\sum b_u^* \otimes \psi(b_u) = (1 \otimes \psi)\Omega_{k-1_i}$, as required. \square

Example 5.3. For $r = 2$, we write t for $t^{(1)}$ and s for $t^{(2)}$. Then $\text{Res}_{s=0} \Omega_{(1,1)} =$

$$\text{Res}_{s=0} \left(\frac{dt}{t} \wedge \frac{d(s-t)}{s-t} \otimes \tilde{f}_2 \tilde{f}_1 - \frac{ds}{s} \wedge \frac{d(t-s)}{t-s} \otimes \tilde{f}_1 \tilde{f}_2 \right) = 0 \otimes \tilde{f}_2 \tilde{f}_1 - \frac{dt}{t} \otimes \tilde{f}_1 \tilde{f}_2 = -\Omega_{(1,0)} \tilde{f}_2.$$

5.2. The multiplication of differential forms. Recall that U_r is equipped with a standard Hopf algebra structure. The co-multiplication $\Delta : U_r \rightarrow U_r \otimes U_r$ is defined for degree one elements x as $\Delta(x) = 1 \otimes x + x \otimes 1$; e.g. $\Delta(\tilde{f}_1) = 1 \otimes \tilde{f}_1 + \tilde{f}_1 \otimes 1$. Then $\Delta(\tilde{f}_1 \tilde{f}_2) = 1 \otimes \tilde{f}_1 \tilde{f}_2 + \tilde{f}_1 \otimes \tilde{f}_2 + \tilde{f}_2 \otimes \tilde{f}_1 + \tilde{f}_1 \tilde{f}_2 \otimes 1$.

The dual Δ^* of Δ is therefore a multiplication on the dual space $U_r^* = \sum_k \mathcal{A}^{G_k}$. Our goal is to express explicitly this multiplication of differential forms.

Theorem 5.4. For $k, l \in \mathbb{N}^r$, let $\omega dV_k \in \mathcal{A}^{G_k}$ and $\eta dV_l \in \mathcal{A}^{G_l}$ be differential forms. Then

$$(5) \quad \Delta^*(\omega dV_k \otimes \eta dV_l) = (\omega * \eta) dV_{k+l},$$

(see Section 2.3).

Proof. We will need the following concept. Call a triple (S_1, S_2, J) a *shuffle* of $J_1 : \{1, \dots, |k|\} \rightarrow \{1, \dots, r\}$ and $J_2 : \{1, \dots, |l|\} \rightarrow \{1, \dots, r\}$ if

- S_1, S_2 are subsets of $\{1, \dots, |k+l|\}$, $\#S_1 = |k|$, $\#S_2 = |l|$,
- $\{1, \dots, |k+l|\}$ is the disjoint union of S_1 and S_2 ,
- J is a map from $\{1, \dots, |k+l|\}$ to $\{1, \dots, r\}$,
- for the increasing bijections $s_1 : S_1 \rightarrow \{1, \dots, |k|\}$ and $s_2 : S_2 \rightarrow \{1, \dots, |l|\}$, we have

$$J(i) = \begin{cases} J_1 \circ s_1(i) & i \in S_1 \\ J_2 \circ s_2(i) & i \in S_2. \end{cases}$$

The collection of \tilde{f}_J 's form a basis of U_r . Let the dual basis of U_r^* be $\{\tilde{f}_J^*\}$. We only need to check (5) for this dual basis. Hence, let $\omega dV_k = \tilde{f}_{J_1}^*$, $\eta dV_l = \tilde{f}_{J_2}^*$ with $\tilde{f}_{J_1} \in U_r[k]$, $\tilde{f}_{J_2} \in U_r[l]$.

The definition of Δ implies that $\Delta^*(\tilde{f}_{J_1}^* \otimes \tilde{f}_{J_2}^*)$ is $\sum \tilde{f}_J^*$, where the summation runs over all shuffles of J_1 and J_2 ; e.g. $\Delta^*(\tilde{f}_1^* \otimes \tilde{f}_2^*) = (\tilde{f}_1 \tilde{f}_2)^* + (\tilde{f}_2 \tilde{f}_1)^*$, $\Delta^*(\tilde{f}_1^* \otimes \tilde{f}_1^*) = 2(\tilde{f}_1^2)^*$.

On the other hand, the right-hand-side in (5) is also $\sum \tilde{f}_J^*$, with the summation running over the shuffles of J_1 and J_2 . This can be seen by an iterated application of the ‘diagram surgery’

The diagram shows an equation between three graphs. The left graph has a central vertex with three edges: one horizontal edge on the left labeled x , one horizontal edge on the top labeled y , and one horizontal edge on the bottom labeled z . The right graph is the sum of two graphs. The first graph on the right has a central vertex with three edges: one horizontal edge on the left labeled x , one horizontal edge on the top labeled y , and one horizontal edge on the right labeled z . The second graph on the right has a central vertex with three edges: one horizontal edge on the left labeled x , one horizontal edge on the top labeled y , and one horizontal edge on the bottom labeled z .

justified by the identity

$$\frac{1}{(y-x)(z-x)} = \frac{1}{(y-x)(z-y)} + \frac{1}{(z-x)(y-z)}.$$

c.f. [MuV, Lemma 4.4]. For example $1/(t(s-t)) * 1/u = 1/(t(s-t)u) =$

$$\begin{array}{c} \begin{array}{c} t \quad s \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ * \quad \bullet \\ \diagup \quad \diagdown \\ \bullet \\ u \end{array} = \begin{array}{c} t \quad s \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ * \quad \bullet \\ \diagup \quad \diagdown \\ \bullet \\ u \end{array} + \begin{array}{c} t \quad s \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ * \quad \bullet \\ \diagup \quad \diagdown \\ \bullet \\ u \end{array} = \left(\begin{array}{c} t \quad s \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ * \quad \bullet \\ \diagup \quad \diagdown \\ \bullet \\ u \end{array} + \begin{array}{c} t \quad s \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ * \quad \bullet \\ \diagup \quad \diagdown \\ \bullet \\ u \end{array} \right) + \begin{array}{c} t \quad s \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ * \quad \bullet \\ \diagup \quad \diagdown \\ \bullet \\ u \end{array} = \end{array}$$

$$= 1/(t(s-t)(u-s)) + 1/(t(u-t)(s-u)) + 1/(u(t-u)(s-t)). \quad \square$$

6. THE CANONICAL DIFFERENTIAL FORM FOR THE SIMPLE LIE ALGEBRAS A, B, C, D

The following projections of the canonical differential form are used in integral solutions of the KZ equations and in the Bethe ansatz construction. Let \mathfrak{g} be a simple Lie algebra of rank r , with Cartan decomposition $\mathfrak{g} = \mathfrak{n}_- \oplus \mathfrak{h} \oplus \mathfrak{n}_+$. The universal enveloping algebra $U(\mathfrak{n}_-)$ of \mathfrak{n}_- is generated by r elements f_1, \dots, f_r (the standard Chevalley generators) subject to the Serre relations; i.e. there is the quotient map $q : U_r \rightarrow U(\mathfrak{n}_-)$ sending \tilde{f}_i to f_i for any i . We say that an element $x \in U(\mathfrak{n}_-)$ has content $k \in \mathbb{N}^r$ if $x \in q(U_r[k])$.

Definition 6.1. *The canonical differential form $\Omega_k^{\mathfrak{g}}$ of a simple Lie algebra \mathfrak{g} is defined as the image of Ω_k under the map*

$$\text{id} \otimes q : \mathcal{A}^{G_k} \otimes U_r[k] \rightarrow \mathcal{A}^{G_k} \otimes U(\mathfrak{n}_-)[k].$$

The Lie algebra \mathfrak{n}_- is a direct sum of 1-dimensional weight spaces \mathfrak{n}_β labelled by the positive roots $\beta : \mathfrak{n}_- = \bigoplus_{\beta} \mathfrak{n}_\beta$. Let F_β be a choice of generator in \mathfrak{n}_β . We fix a linear ordering of the positive roots: β_1, \dots, β_m . According to the Poincaré-Birkhoff-Witt theorem, a \mathbb{C} -basis of the algebra $U(\mathfrak{n}_-)$ is given by the collection of elements $F_{\beta_1}^{p_1} F_{\beta_2}^{p_2} \dots F_{\beta_m}^{p_m}$, where $m = \dim \mathfrak{n}_-$ and $p = (p_1, \dots, p_m) \in \mathbb{N}^m$.

Example 6.2. For sl_3 , the Lie algebra of all 3×3 matrices with trace equal to zero, the positive roots $\alpha_1, \alpha_2, \alpha_1 + \alpha_2$ correspond to the matrix entries at the positions $(2, 1), (3, 2),$ and $(3, 1)$, and in turn, to the basis $F_{\alpha_1} = f_1, F_{\alpha_2} = f_2, F_{\alpha_1 + \alpha_2} = [f_2, f_1]$ of \mathfrak{n}_- . A PBW basis of $U(\mathfrak{n}_-)$ is $f_1^{p_1} [f_2, f_1]^{p_2} f_2^{p_3}$ with $p = (p_1, p_2, p_3) \in \mathbb{N}^3$.

After fixing the linear ordering $\beta_1 < \beta_2 < \dots < \beta_m$ of the positive roots of \mathfrak{g} , the canonical differential form of \mathfrak{g} can be written in the form of

$$(6) \quad \Omega_k^{\mathfrak{g}} = \sum_p \omega_p dV_k \otimes F_{\beta_1}^{p_1} F_{\beta_2}^{p_2} \dots F_{\beta_m}^{p_m}.$$

Here the summation is over p such that the content of $F_{\beta_1}^{p_1} F_{\beta_2}^{p_2} \dots F_{\beta_m}^{p_m}$ is k ; $\omega_p dV_k$ is a differential form in \mathcal{A}^{G_k} , and ω_p is a rational function.

Theorem 6.3. (Product formula.) For $l = 1, \dots, m$, let the content of F_{β_l} be $k^{(l)}$. Then there exist rational functions η_{β_l} in the variables $(t_j^{(i)})_{j=1, \dots, k_i^{(l)}}$, symmetric under $G_{k^{(l)}}$, such that

$$\omega_p = \frac{1}{\prod_l p_l!} \cdot \overbrace{\eta_{\beta_1} * \dots * \eta_{\beta_1}}^{p_1} * \overbrace{\eta_{\beta_2} * \dots * \eta_{\beta_2}}^{p_2} * \dots * \overbrace{\eta_{\beta_m} * \dots * \eta_{\beta_m}}^{p_m}$$

Proof. Denote $F^p = F_{\beta_1}^{p_1} \dots F_{\beta_m}^{p_m}$. The co-multiplication Δ can be expressed in the PBW basis as:

$$\Delta(F^p) = \sum_{p'+p''=p} \prod_{i=1}^m \frac{p_i!}{p_i'! p_i''!} \cdot F^{p'} \otimes F^{p''}.$$

Then for the dual multiplication we have

$$\Delta^*(\omega_{p'} dV_k \otimes \omega_{p''} dV_l) = \Delta^*(F^{p'*} \otimes F^{p''*}) = \left(\prod_i \frac{(p_i' + p_i'')!}{p_i'! p_i''!} \right) \cdot F^{(p'+p'')*}.$$

Using Theorem 5.4, we obtain

$$\omega_{p'} * \omega_{p''} = \prod_i \frac{(p_i' + p_i'')!}{p_i'! p_i''!} \cdot \omega_{p'+p''},$$

from which the result follows (put $\eta_{\beta_l} = \omega_{1_l}$). \square

Example 6.4. For $\mathfrak{g} = sl_3$ and the ordering $\alpha_1 < \alpha_1 + \alpha_2 < \alpha_2$, we have $\omega_{\alpha_1} = 1/t_1$, $\omega_{\alpha_1 + \alpha_2} = 1/(t_1(s_1 - t_1))$ and $\omega_{\alpha_2} = 1/s_1$. (Again, we write t for $t^{(1)}$ and s for $t^{(2)}$.) Then the differential form corresponding to $f_1^2[f_2, f_1]$ is

$$\begin{aligned} \omega_{(2,1,0)} dt_1 \wedge dt_2 \wedge dt_3 \wedge ds &= \frac{1}{2!1!0!} \cdot \frac{1}{t_1} * \frac{1}{t_1} * \frac{1}{t_1(s_1 - t_1)} = \\ &= \frac{1}{2} \text{Sym}_{(3,1)} \left(\frac{1}{t_1 t_2 t_3 (s - t_3)} \right) dV_{(3,1)} = \frac{3s^2 - 2s(t_1 + t_2 + t_3) + (t_1 t_2 + t_1 t_3 + t_2 t_3)}{t_1 t_2 t_3 (s - t_1)(s - t_2)(s - t_3)} dV_{(3,1)}. \end{aligned}$$

This means that $\Omega_k^{\mathfrak{g}}$ is determined once we know its ‘atoms’, i.e. the η_{β} ’s for the positive roots β . In the remainder of this section, we will compute them for the infinite series A, B, C, D of simple Lie algebras. For each of these, we will list (1) the positive roots, (2) the simple roots, and (3) the expression of the positive roots in terms of the simple roots. Then we choose (4) a linear ordering of the positive roots and fix (5) the elements F_{β} ’s (choice of a constant). Then we describe the elements η_{β} ’s with the choices (4), (5).

Let $\epsilon_i = (0, \dots, 0, 1, 0, \dots, 0) \in \mathbb{C}^r$ (1 occurs at the i th position from the left). For a multi-index $J = (J(1), J(2), \dots, J(n))$, let $[f_J] = [f_{J(1)}, [f_{J(2)}, [\dots, [f_{J(n-1)}, f_{J(n)}] \dots]]]$.

6.1. The simple Lie algebra A_{r-1} .

- (1) The positive roots are $\epsilon_i - \epsilon_j$ for $1 \leq i < j \leq r$.
- (2) The simple roots are $\alpha_i = \epsilon_i - \epsilon_{i+1}$ for $1 \leq i < r$.
- (3) $\epsilon_i - \epsilon_j = \sum_{u=i}^{j-1} \alpha_u$.
- (4) Let $\epsilon_i - \epsilon_j < \epsilon_{i'} - \epsilon_{j'}$ if either $i < i'$, or $i = i'$ and $j < j'$.
- (5) For a positive root $\beta = \epsilon_i - \epsilon_j$, let $F_{\beta} = [f_{(j-1, j-2, \dots, i)}]$.

Theorem 6.5. For $\beta = \epsilon_i - \epsilon_j = \alpha_i + \alpha_{i+1} + \dots + \alpha_{j-1}$, we have

$$\eta_\beta = \frac{1}{t_1^{(i)}(t_1^{(i+1)} - t_1^{(i)}) \cdot \dots \cdot (t_1^{(j-1)} - t_1^{(j-2)})}.$$

The result can be visualized by the following string-diagram (the labels of the vertices in the diagram indicate the superscripts of the corresponding t_1 's).

$$\eta_{\alpha_i + \dots + \alpha_j} = * \overset{i}{\bullet} \overset{i+1}{\bullet} \dots \overset{j-1}{\bullet}$$

6.2. The simple Lie algebra B_r .

- (1) The positive roots are ϵ_i ($1 \leq i \leq r$) and $\epsilon_i - \epsilon_j$, $\epsilon_i + \epsilon_j$ ($1 \leq i < j \leq r$).
- (2) The simple roots are $\alpha_i = \epsilon_i - \epsilon_{i+1}$ for $i = 1, \dots, r-1$ and $\alpha_r = \epsilon_r$ (the 'short' root).
- (3)

$$\epsilon_i = \sum_{u=i}^r \alpha_u \quad (1 \leq i \leq r), \quad \epsilon_i - \epsilon_j = \sum_{u=i}^{j-1} \alpha_u, \quad \epsilon_i + \epsilon_j = \sum_{u=i}^{j-1} \alpha_u + 2 \sum_{u=j}^r \alpha_u \quad (1 \leq i < j \leq r).$$

- (4) Let β be one of ϵ_i , $\epsilon_i - \epsilon_j$, or $\epsilon_i + \epsilon_j$, and let β' be one of $\epsilon_{i'}$, $\epsilon_{i'} - \epsilon_{j'}$, or $\epsilon_{i'} + \epsilon_{j'}$. Then we set $\beta < \beta'$ if $i > i'$. If $i < j < j'$ then we also set $\epsilon_i + \epsilon_j < \epsilon_i + \epsilon_{j'} < \epsilon_i < \epsilon_i - \epsilon_{j'} < \epsilon_i - \epsilon_j$.
- (5) $F_{\alpha_i + \dots + \alpha_{j-1}} = [f_{(j-1, j-2, \dots, i)}]$ and $F_{\epsilon_i + \epsilon_j} = [[f_{(i, i+1, \dots, r)}], [f_{(r, r-1, \dots, j)}]]$.

The vector $(\overbrace{0, \dots, 0}^{u_0}, \overbrace{1, \dots, 1}^{u_1}, \dots)$ will be abbreviated by $(0^{u_0} 1^{u_1} \dots)$.

Theorem 6.6. We have

$$\eta_{\alpha_i + \dots + \alpha_{j-1}} = \frac{1}{t_1^{(j-1)}(t_1^{(j-2)} - t_1^{(j-1)}) \cdot \dots \cdot (t_1^{(i)} - t_1^{(i+1)})} \quad (\text{for both roots } \epsilon_i \text{ and } \epsilon_i - \epsilon_j),$$

$$\eta_{\epsilon_i + \epsilon_j} = \frac{1}{2} \text{Sym}_{(0^{i-1} 1^{j-i} 2^{r-j+1})} \left(\frac{t_1^{(r-1)} - t_2^{(r-1)}}{t_1^{(j)}(t_1^{(r)} - t_1^{(r-1)})(t_2^{(r)} - t_1^{(r-1)})(t_2^{(r-1)} - t_1^{(r)})(t_2^{(r-1)} - t_2^{(r)})} \right. \\ \left. \cdot \frac{1}{\prod_{k=j+1}^{r-1} (t_1^{(k)} - t_1^{(k-1)}) \prod_{k=i}^{r-2} (t_2^{(k)} - t_2^{(k+1)})} \right).$$

The structure of these functions is better understood via the following pictures.

$$\eta_{\alpha_i + \dots + \alpha_{j-1}} = * \overset{j-1}{\bullet} \overset{j-2}{\bullet} \dots \overset{i}{\bullet}$$

$$\eta_{\sum_{i \leq k < j} \alpha_k + 2 \sum_{j \leq k \leq r} \alpha_k} = \frac{1}{2} \text{Sym} \quad * \overset{j}{\bullet} \overset{j+1}{\bullet} \dots \overset{r-1}{\bullet} \begin{array}{c} \overset{r}{\bullet} \\ \swarrow \quad \searrow \\ \overset{r-1}{\bullet} \quad \overset{r-1}{\bullet} \\ \nwarrow \quad \nearrow \\ \overset{r}{\bullet} \end{array} \overset{r-2}{\bullet} \dots \overset{i}{\bullet}$$

In the second picture, the double edge means that the corresponding difference is in the numerator. The labels mean superscripts of variables t_1 , and when a superscript i is used twice in a diagram, they mean $t_1^{(i)}$ and $t_2^{(i)}$.

6.3. The simple Lie algebra C_r .

- (1) The positive roots are $\epsilon_i - \epsilon_j$, $\epsilon_i + \epsilon_j$ for $1 \leq i < j \leq r$ and $2\epsilon_i$ for $1 \leq i \leq r$.
- (2) The simple roots are $\alpha_i = \epsilon_i - \epsilon_{i+1}$ ($1 \leq i < r$) and $\alpha_r = 2\epsilon_r$ (the ‘long’ root).
- (3)

$$\epsilon_i - \epsilon_j = \sum_{u=i}^{j-1} \alpha_u, \quad \epsilon_i + \epsilon_j = \sum_{u=i}^{j-1} \alpha_u + 2 \sum_{u=j}^{r-1} \alpha_u + \alpha_r, \quad 2\epsilon_i = 2 \sum_{u=i}^{r-1} \alpha_u + \alpha_r.$$

- (4) Let β be one of $\epsilon_i - \epsilon_j$, $\epsilon_i + \epsilon_j$, or $2\epsilon_i$, and let β' be one of $\epsilon_{i'} - \epsilon_{j'}$, $\epsilon_{i'} + \epsilon_{j'}$, or $2\epsilon_{i'}$. Then we set $\beta < \beta'$ if $i > i'$. For $i < j < j'$ we also set $\epsilon_i + \epsilon_j < \epsilon_i + \epsilon_{j'} < 2\epsilon_i < \epsilon_i - \epsilon_{j'} < \epsilon_i - \epsilon_j$.
- (5) $F_{\epsilon_i - \epsilon_j} = [f_{(i,i+1,\dots,j-1)}]$, $F_{\epsilon_i + \epsilon_j} = [f_{(i,i+1,\dots,r-1,r,r-1,\dots,j)}]$, $F_{2\epsilon_i} = [[f_{(i,i+1,\dots,r-1)}], [f_{(i,i+1,\dots,r)}]]$.

Theorem 6.7. *We have*

$$\begin{aligned} \eta_{\epsilon_i - \epsilon_j} &= \frac{1}{t_1^{(j-1)} \prod_{u=i}^{j-2} (t_1^{(u)} - t_1^{(u+1)})}, \\ \eta_{\epsilon_i + \epsilon_j} &= \text{Sym}_{(0^{i-1}1^{j-i}2^{r-j})} \left(\frac{1}{t_1^{(j-1)} \prod_{u=j+1}^r (t_1^{(u)} - t_1^{(u-1)}) \prod_{u=i}^{r-1} (t_2^{(u)} - t_2^{(u+1)})} \right), \\ \eta_{2\epsilon_i} &= \text{Sym}_{(0^{i-1}2^{r-i})} \left(\frac{1}{t_1^{(r)} (t_1^{(r-1)} - t_1^{(r)}) (t_2^{(r-1)} - t_1^{(r)}) \prod_{u=i}^{r-2} (t_1^{(u)} - t_1^{(u+1)}) \prod_{u=i}^{r-2} (t_2^{(u)} - t_2^{(u+1)})} \right). \end{aligned}$$

The result can be visualized by the following diagrams (labels mean upper indices).

$$\begin{aligned} \eta_{\epsilon_i - \epsilon_j} &= * \overset{j-1}{\bullet} \overset{j-2}{\bullet} \dots \overset{i}{\bullet} \\ \eta_{\epsilon_i + \epsilon_j} &= \text{Sym} * \overset{j}{\bullet} \overset{j+1}{\bullet} \dots \overset{r-1}{\bullet} \overset{r}{\bullet} \overset{r-1}{\bullet} \overset{r-2}{\bullet} \dots \overset{i}{\bullet} \\ \eta_{2\epsilon_i} &= \text{Sym} * \begin{array}{c} \overset{r-1}{\bullet} \overset{r-2}{\bullet} \dots \overset{i}{\bullet} \\ \bullet \overset{r}{\bullet} \\ \underset{r-1}{\bullet} \underset{r-2}{\bullet} \dots \underset{i}{\bullet} \end{array} \end{aligned}$$

6.4. The simple Lie algebra D_r .

- (1) The positive roots are $\epsilon_j - \epsilon_i$ and $\epsilon_j + \epsilon_i$ for $1 \leq i < j \leq r$.
- (2) The simple roots are $\alpha_1 = \epsilon_1 + \epsilon_2$ and $\alpha_i = \epsilon_i - \epsilon_{i-1}$ ($1 < i \leq r$).
- (3)

$$\epsilon_j - \epsilon_i = \sum_{u=i+1}^j \alpha_u, \quad \epsilon_i + \epsilon_j = \alpha_1 + \alpha_2 + 2 \sum_{u=3}^i \alpha_u + \sum_{u=i+1}^j \alpha_u \quad (1 < i < j \leq r), \quad \epsilon_1 + \epsilon_j = \alpha_1 + \sum_{u=3}^j \alpha_u.$$

- (4) Let β be one of $\epsilon_j - \epsilon_i$ or $\epsilon_j + \epsilon_i$, and let β' be one of $\epsilon_{j'} - \epsilon_{i'}$ or $\epsilon_{j'} + \epsilon_{i'}$. Then we set $\beta < \beta'$ if $j < j'$. For $i' < i < j$ we also set $\epsilon_j + \epsilon_i < \epsilon_j + \epsilon_{i'} < \epsilon_j - \epsilon_{i'} < \epsilon_j - \epsilon_i$.
- (5) $F_{\epsilon_j - \epsilon_i} = [f_{(j,j-1,\dots,i+1)}]$, $F_{\epsilon_1 + \epsilon_j} = [f_{(j,j-1,\dots,3,1)}]$, $F_{\epsilon_i + \epsilon_j} = [f_{(j,j-1,\dots,2,1,3,4,\dots,i-1,i)}]$.

Theorem 6.8. *We have*

$$\eta_{\epsilon_j - \epsilon_i} = \frac{1}{t_1^{(i+1)} \prod_{u=i+2}^j (t_1^{(u)} - t_1^{(u-1)})},$$

$$\eta_{\epsilon_j + \epsilon_1} = \frac{1}{t_1^{(1)} \prod_{u=3}^j (t_1^{(u)} - t_1^{(u-1)})}.$$

For $1 < i < j$, $\eta_{\epsilon_j + \epsilon_i} = \text{Sym}_{(1^2 2^{i-2} 1^{j-i} 0^{r-j})}$

$$\frac{t_1^{(3)} - t_2^{(3)}}{t_2^{(i)} (t_1^{(1)} - t_2^{(3)}) (t_1^{(2)} - t_2^{(3)}) (t_1^{(3)} - t_1^{(1)}) (t_1^{(3)} - t_1^{(2)}) \prod_{u=3}^{i+1} (t_2^{(u)} - t_2^{(u+1)}) \prod_{u=4}^j (t_1^{(u)} - t_1^{(u-1)})}.$$

The result can be visualized by the following diagrams (labels mean upper indices).

$$\begin{aligned} \eta_{\epsilon_j - \epsilon_i} &= * \overset{i+1}{\bullet} \overset{i+2}{\bullet} \dots \overset{j}{\bullet} \\ \eta_{\epsilon_j + \epsilon_1} &= * \overset{1}{\bullet} \overset{3}{\bullet} \dots \overset{j}{\bullet} \\ \eta_{\epsilon_j + \epsilon_i} &= \text{Sym}_k * \overset{i}{\bullet} \overset{i-1}{\bullet} \dots \overset{3}{\bullet} \begin{array}{c} \overset{1}{\bullet} \\ \diagup \quad \diagdown \\ \bullet \quad \bullet \\ \diagdown \quad \diagup \\ \overset{2}{\bullet} \end{array} \overset{4}{\bullet} \dots \overset{j}{\bullet} \end{aligned}$$

6.5. The proofs of the theorems 6.5-6.8. Let \mathfrak{g} be one of the simple Lie algebras A_r , B_r , C_r , D_r , and let β be one of its positive roots. In one of the Theorems 6.5–6.8 (the one referring to \mathfrak{g}), we state a formula for η_β ; let us denote the function on the right-hand-side of that formula by $\bar{\eta}_\beta$. In this section we will prove that $\eta_\beta = \bar{\eta}_\beta$, by proving Theorems 6.10 and 6.12 below.

Lemma 6.9. *Under the correspondence between $U_r[k]$ and Fl^{G_k} of Section 3.5, we have*

$$\begin{aligned} [\tilde{f}_i, \tilde{f}_j] &\leftrightarrow \pm [\mathbb{C}^{|k|} \supset (t_1^{(i)} = t_1^{(j)}) \supset (t_1^{(i)} = t_1^{(j)} = 0)] \\ [\tilde{f}_i, [\tilde{f}_i, \tilde{f}_j]] &\leftrightarrow \pm \text{ASym}_{(2,1)} \left([\mathbb{C}^{|k|} \supset (t_1^{(i)} = t_1^{(j)}) \supset (t_1^{(i)} = t_2^{(i)} = t_1^{(j)}) \supset (t_1^{(i)} = t_2^{(i)} = t_1^{(j)} = 0)] \right) \\ [\tilde{f}_i, [\tilde{f}_i, [\tilde{f}_i, \tilde{f}_j]]] &\leftrightarrow \\ &\pm \text{ASym}_{(3,1)} \left([\mathbb{C}^{|k|} \supset (t_1^{(i)} = t_1^{(j)}) \supset (t_1^{(i)} = t_1^{(j)} = t_2^{(i)}) \supset (t_1^{(i)} = t_1^{(j)} = t_2^{(i)} = t_3^{(i)}) \supset (t_1^{(i)} = t_1^{(j)} = t_2^{(i)} = t_3^{(i)} = 0)] \right). \end{aligned}$$

Proof. For $i < j$ let $L = (t_1^{(i)} = t_1^{(j)} = 0)$. Then we have

$$\tilde{f}_i \tilde{f}_j - \tilde{f}_j \tilde{f}_i \leftrightarrow -[\mathbb{C}^{|k|} \supset (t_1^{(j)} = 0) \supset L] - [\mathbb{C}^{|k|} \supset (t_1^{(i)} = 0) \supset L] = [\mathbb{C}^{|k|} \supset (t_1^{(j)} = t_1^{(i)}) \supset L],$$

which proves the first statement. The others follow from similar calculations. \square

Let the content of F_β be k .

Theorem 6.10. *Let $F \in Fl^{G_k}$ be a linear combination of flags corresponding to an element $\sum c_J f_J$ in $U_r[k]$ of content k . If $\sum_j c_j f_j$ belongs to the ideal generated by the Serre relations, then $\text{Res}_F \bar{\eta}_\beta dV_k = 0$.*

Proof. We show the result for \mathfrak{g} of type A . In this case there are two kinds of Serre relations: $[f_i, f_j] = 0$ if $(\alpha_i, \alpha_j) = 0$, and $[f_i, [f_i, f_j]] = 0$ if $(\alpha_i, \alpha_j) = -1$. We will consider the linear combination of flags corresponding to multiples of $[\tilde{f}_i, \tilde{f}_j]$ and $[\tilde{f}_i, [\tilde{f}_i, \tilde{f}_j]]$. By Lemma 6.9, any multiple of $[\tilde{f}_i, \tilde{f}_j]$ corresponds to a linear combination F of flags of the form $\pm[\mathbb{C}^{|k|} \supset \dots \supset L_{u+2} \supset L_{u+1} \supset L_u \supset \dots \supset 0]$ with

$$[L_{u+2}/L_u \supset L_{u+1}/L_u \supset L_u/L_u] \simeq [\mathbb{C}^2 \supset (t_{v_1}^{(i)} = t_{v_2}^{(j)}) \supset 0],$$

where the coordinates on \mathbb{C}^2 are $t_{v_1}^{(i)}$ and $t_{v_2}^{(j)}$.

The rational function $\bar{\eta}_\beta$ does not have a factor of type $t^{(i)} - t^{(j)}$ in the denominator for $(\alpha_i, \alpha_j) = 0$. Thus $\text{Res}_F \bar{\eta}_\beta dV_k = 0$.

By Lemma 6.9, any multiple of $[\tilde{f}_i[\tilde{f}_i, \tilde{f}_j]]$ corresponds to a linear combination F of flags, with each term of the form $\pm[\mathbb{C}^{|k|} \supset \dots \supset L_{u+3} \supset L_{u+2} \supset L_{u+1} \supset L_u \supset \dots \supset 0]$ with

$$[L_{u+3}/L_u \supset L_{u+2}/L_u \supset L_{u+1}/L_u \supset L_u/L_u] \simeq [\mathbb{C}^3 \supset (t_{v_1}^{(i)} - t_{v_2}^{(j)}) \supset (t_{v_1}^{(i)} = t_{v_3}^{(i)} = t_{v_2}^{(j)}) \supset 0],$$

where the coordinates on \mathbb{C}^3 are $t_{v_1}^{(i)}$, $t_{v_3}^{(i)}$, and $t_{v_2}^{(j)}$ with $v_1 \neq v_3$. Since all k_i are 0 or 1 for the positive root β , this type of flags cannot occur in Fl^{G_k} .

The proof for the types B, C, D are analogous. \square

Remark 6.11. By Theorem 6.10, the differential forms $\Omega^{\mathfrak{g}}$ (and Ω^V , see the Introduction and Section 7 below) do not have poles at the $t^{(i)} = t^{(j)}$ type hyperplanes if the corresponding simple roots are orthogonal. Hence the poles of $\Omega^{\mathfrak{g}}$ coincide with the singularities of the master function, see the Introduction.

Now let $F^p = F_{\beta_1}^{p_1} \dots F_{\beta_m}^{p_m}$ be another element of content k in the Poincare-Birkhoff-Witt basis, different from F_β . Let us choose preimages of F_β and F^p under the projection $U_r[k] \rightarrow U(\mathfrak{n}_-)$, and let $Flag_\beta$ and $Flag^p \in Fl^{G_k}$ be the corresponding linear combinations of flags.

Theorem 6.12.

- The residue of the differential form $\bar{\eta}_\beta dV_k$ with respect to $Flag^p$ is 0.
- The residue of the differential form $\bar{\eta}_\beta dV_k$ with respect to $Flag_\beta$ is 1.

Lemma 6.13. For $i = 1, \dots, r$, $j = 1, \dots, k_i$, we have

$$\text{Res}_{t_j^{(i)}=0} \eta_\beta dV_k = \text{Res}_{t_j^{(i)}=0} \bar{\eta}_\beta dV_k .$$

Proof. It is enough to consider $j = k_i$. Then the left hand side can be calculated from Theorem 5.2, and the right hand side is given explicitly. For types A, B, D , we obtain

$$\text{Res}_{t_1^{(i)}=0} \eta_\beta dV_k = \text{Res}_{t_1^{(i)}=0} \bar{\eta}_\beta dV_k = \begin{cases} \eta_{\beta-\alpha_i} dV_{k-1_i} & \text{if } \beta - \alpha_i \text{ is a positive root, } \beta - \alpha_i > \beta \\ 0 & \text{otherwise.} \end{cases}$$

For type C we obtain $\text{Res}_{t_1^{(i)}=0} \eta_\beta dV_k = \text{Res}_{t_1^{(i)}=0} \bar{\eta}_\beta dV_k =$

$$= \begin{cases} \eta_{\beta-\alpha_i} dV_{k-1_i} & \text{if } \beta - \alpha_i \text{ is a positive root, } \beta - \alpha_i > \beta \\ \eta_{\frac{\beta-\alpha_i}{2}} * \eta_{\frac{\beta-\alpha_i}{2}} dV_{k-1_i} & \text{if } \frac{\beta-\alpha_i}{2} \text{ is a positive root, } \frac{\beta-\alpha_i}{2} > \beta \\ 0 & \text{otherwise.} \end{cases}$$

\square

Proof of Theorem 6.12. The second statement follows from the explicit forms for $\bar{\eta}_\beta$.

Let $\bar{\Omega}_k^{\mathfrak{g}}$ be the form obtained from $\Omega_k^{\mathfrak{g}}$ by replacing the term $\eta_\beta \otimes F_\beta$ by $\bar{\eta}_\beta \otimes F_\beta$. Then $\text{Res}_{\text{Flag}^p} \bar{\Omega}_k^{\mathfrak{g}} = \text{Res}_{\text{Flag}^p} \Omega_k^{\mathfrak{g}}$ by Lemma 6.13. We have $\text{Res}_{\text{Flag}^p} \Omega_k^{\mathfrak{g}} = 1 \otimes F^p$ by the fact $(U_r[k])^* = \mathcal{A}^{G^k}$. Therefore we have $\text{Res}_{\text{Flag}^p} \bar{\eta}_\beta = 0$, as required. \square

7. APPENDIX: REPRESENTATION-VALUED CANONICAL DIFFERENTIAL FORM

For the convenience of the reader, we give formulas from [SV1], [SV2] for the V -valued differential form Ω^V which appears in the hypergeometric solutions to the KZ equations and the Bethe ansatz method.

Consider the formula for the canonical differential form from Theorem 4.1, without putting $t_0 = 0$. Instead, put $t_0 = z$ and denote this form by $\Omega_k(z)$, e.g. $\Omega_{(1,1)}(z) = \frac{dt}{t-z} \wedge \frac{ds}{s-t}$. The projection to \mathfrak{g} of this form will be denoted by $\Omega_k^{\mathfrak{g}}(z)$.

The proofs in Section 6 can be modified to get PBW expansions of $\Omega_k^{\mathfrak{g}}(z)$. The only change in the PBW-coefficient results is that the $*$ of the diagrams has to be decorated by z (instead of 0). E.g. for $k = (2)$, instead of $\text{ASym}_{(2)}(dt_1/t_1 \wedge d(t_2 - t_1)/(t_2 - t_1)) = 1/(t_1 t_2) dt_1 \wedge dt_2$ we have $\text{ASym}_{(2)}(dt_1/(t_1 - z) \wedge d(t_2 - t_1)/(t_2 - t_1)) = 1/((t_1 - z)(t_2 - z)) dt_1 \wedge dt_2$. For a simple Lie algebra \mathfrak{g} , let V_Λ be a highest weight \mathfrak{g} -module with highest weight $\Lambda \in \mathfrak{h}^*$ and generating vector v_Λ . Recall that the map $U(\mathfrak{n}_-) \rightarrow V_\Lambda$, $x \rightarrow x \cdot v_\Lambda$ is surjective.

Definition 7.1. Let $k^{(1)}, k^{(2)}, \dots, k^{(n)} \in \mathbb{N}^r$, $k = \sum k^{(i)}$. We extend the star multiplication from Section 2.3 as follows:

$$* : (\mathcal{A}^{G_{k^{(1)}}} \otimes V_{\Lambda_1}) \otimes (\mathcal{A}^{G_{k^{(2)}}} \otimes V_{\Lambda_2}) \otimes \dots \otimes (\mathcal{A}^{G_{k^{(n)}}} \otimes V_{\Lambda_n}) \rightarrow \mathcal{A}^{G_k} \otimes (V_{\Lambda_1} \otimes V_{\Lambda_2} \otimes \dots \otimes V_{\Lambda_n})$$

by

$$(\Omega_1 \otimes v_1) * (\Omega_2 \otimes v_2) * \dots * (\Omega_n \otimes v_n) = (\omega_1 * \dots * \omega_n) dV_k \otimes (v_1 \otimes v_2 \otimes \dots \otimes v_n),$$

where $\Omega_i = \omega_i dV_{k^{(i)}}$.

Let $V = V_{\Lambda_1} \otimes \dots \otimes V_{\Lambda_n}$. We define the V -valued differential form of degree k (c.f. [MuV, (4)]) by

$$\Omega_k^V = \bigoplus_{k^{(1)} + \dots + k^{(n)} = k} \Omega_{k^{(1)}}^{\mathfrak{g}}(z_1) v_{\Lambda_1} * \dots * \Omega_{k^{(n)}}^{\mathfrak{g}}(z_n) v_{\Lambda_n}.$$

Example 7.2. For $n = 2$, $r = 1$ (i.e. $\mathfrak{g} = \mathfrak{sl}_2$), we have

$$\Omega_{(2)}^V = \Omega_{(2)}^{\mathfrak{g}}(z_1) v_{\Lambda_1} * \Omega_{(0)}^{\mathfrak{g}}(z_2) v_{\Lambda_2} + \Omega_{(1)}^{\mathfrak{g}}(z_1) v_{\Lambda_1} * \Omega_{(1)}^{\mathfrak{g}}(z_2) v_{\Lambda_2} + \Omega_{(0)}^{\mathfrak{g}}(z_1) v_{\Lambda_1} * \Omega_{(2)}^{\mathfrak{g}}(z_2) v_{\Lambda_2} =$$

$$\begin{aligned} & \text{ASym}_{(2)} \left(\frac{dt_1}{t_1 - z_1} \wedge \frac{d(t_2 - t_1)}{t_2 - t_1} \right) \otimes f^2 v_{\Lambda_1} \otimes v_{\Lambda_1} + \\ & \text{ASym}_{(2)} \left(\frac{dt_1}{t_1 - z_1} \wedge \frac{dt_2}{t_2 - z_2} \right) \otimes f v_{\Lambda_1} \otimes f v_{\Lambda_2} + \\ & \text{ASym}_{(2)} \left(\frac{dt_1}{t_1 - z_2} \wedge \frac{d(t_2 - t_1)}{t_2 - t_1} \right) \otimes v_{\Lambda_1} \otimes f^2 v_{\Lambda_2}. \end{aligned}$$

This can be visualized by a diagram

$$\Omega_{(2)}^V = \begin{array}{c} \bullet \\ \swarrow \quad \searrow \\ z_1 \quad 1 \\ * \quad \bullet \\ \swarrow \quad \searrow \\ z_2 \quad 1 \\ * \quad \bullet \end{array} (f^2 v_{\Lambda_1} \otimes v_{\Lambda_2}) + \text{ASym} \left(\begin{array}{c} z_1 \quad 1 \\ * \quad \bullet \\ z_2 \quad 1 \\ * \quad \bullet \end{array} \right) (f v_{\Lambda_1} \otimes f v_{\Lambda_2}) + \begin{array}{c} z_1 \quad 1 \\ * \quad \bullet \\ \swarrow \quad \searrow \\ z_2 \quad 1 \\ * \quad \bullet \end{array} (v_{\Lambda_1} \otimes f^2 v_{\Lambda_2}),$$

where we also used the PBW expansions from Section 6.1.

REFERENCES

- [Ch] I. Cherednik. Integral solutions of Knizhnik-Zamolodchikov equations and Kac-Moody algebras. *Publ. Res. Inst. Math. Sci.*, 27(no. 5):727–744, 1991.
- [FV] G. Felder and A. Varchenko. Integral representation of solutions of the elliptic Knizhnik-Zamolodchikov-Bernard equations. *Int. Math. Res. notices*, (N. 5):221–233, 1995.
- [Mat] A. Matsuo. An application of Aomoto-Gelfand hypergeometric functions to the $\mathfrak{su}(n)$ Knizhnik-Zamolodchikov equation. *Comm. Math. Phys.*, 134(1):65–77, 1990.
- [MaV] Y. Markov and A. Varchenko. Hypergeometric solutions of trigonometric KZ equations satisfy dynamical difference equations. *Adv. Math.*, 166(no. 1):100–147, 2002.
- [MuV] E. Mukhin and A. Varchenko. Norm of the Bethe vector and the Hessian of the master function. AG/0402349, 2004.
- [OT] P. Orlik and H. Terao. Arrangements of Hyperplanes. Springer-Verlag, Berlin, 1992.
- [RV] N. Reshetikhin and A. Varchenko. Quasiclassical asymptotics of solutions to the KZ equations. In *Geometry, Topology and Physics for R. Bott*, pages 293–322, 1995.
- [SV1] V. Schechtman and A. Varchenko. Hypergeometric Solutions of Knizhnik-Zamolodchikov Equations. *Letters in Math. Physics* 20, (1990), 279–283.
- [SV2] V. Schechtman and A. Varchenko. Arrangements of hyperplanes and Lie algebra homology. *Invent. Math.*, 106(1):139–194, 1991.
- [TV1] V. Tarasov and A. Varchenko. Geometry of q -hypergeometric functions as a bridge between Yangians and quantum affine algebras. *Invent. Math.*, 128:501–588, 1997.
- [TV2] V. Tarasov and A. Varchenko. Solutions of the q KZ equations associated with sl_{r+1} , 2004. in preparation.
- [V1] A. Varchenko. *Multidimensional Hypergeometric Functions and Representation Theory of Lie Algebras and Quantum Groups*, volume Vol. 21 of *Advanced Series in Mathematical Physics*. World Scientific, 1995.
- [V2] A. Varchenko. *Special functions, KZ type equations, and representation theory*. Number 98 in CBMS. AMS, 2003.

DEPARTMENT OF MATHEMATICS, UNIVERSITY OF NORTH CAROLINA AT CHAPEL HILL
E-mail address: rimanyi@email.unc.edu

DEPARTMENT OF MATHEMATICS, UNIVERSITA' DI ROMA "LA SAPIENZA"
E-mail address: stevens@mat.uniroma1.it

DEPARTMENT OF MATHEMATICS, UNIVERSITY OF NORTH CAROLINA AT CHAPEL HILL
E-mail address: anv@email.unc.edu